Dynamical Systems and Chaos Part II: Biology Applications

Lecture 12: Stochastic dynamical systems.

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Stochastic Modeling of chemical reactions

▶ Deterministic differential equations (ODEs)

- ▶ In many cases, the time-evolution of a chemically reacting system can be treated as continuous-state, deterministic process.
- ODEs characterize the time-evolution of chemical species as continuous deterministic process.
- Qualitative method. Can be used when concentrations are large.

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▶ Deterministic differential equations (ODEs)

- Each equation expresses the time-rate-of-change of the continuous molecular concentration of one chemical species as a function of the molecular concentrations of all the species.
- ▶ Rate constants are viewed as "reaction rates".
- ▶ Fast to simulate. Produce the same result for the same initial conditions.

$$\begin{array}{l} \mathbf{X}_1 + \mathbf{X}_2 \xrightarrow{k_1} \mathbf{X}_3, \\ v = \frac{\mathrm{d}[\mathbf{X}_3]}{\mathrm{d}t} = -\frac{\mathrm{d}[\mathbf{X}_1]}{\mathrm{d}t} = -\frac{\mathrm{d}[\mathbf{X}_2]}{\mathrm{d}t} = k_1[\mathbf{X}_1][\mathbf{X}_2] \\ \\ \mathrm{d}\mathbf{X}(t) = \mathbf{Sv}\big(\mathbf{K}, \mathbf{X}(t)\big)\mathrm{d}t \end{array}$$

• X is the vector of variables $([X_1], [X_2], and [X_3])$.

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- **S** is the stoichiometric matrix.
- **v** is the vector of reaction rates.
- **K** is the matrix of rate constants.

Stochastic modeling

- ► A chemical reaction occurs whenever two or more molecules of appropriate kinds collide in an appropriate way.
- Collisions in a system of molecules in thermal equilibrium occur in a random way.
- Gillespie stochastic simulation algorithm (SSA) characterizes the time-evolution of chemical species as discrete-state stochastic process. SSA numerically simulates the Markov process that the Chemical Master Equation describes analytically.
 - ▶ The time-evolution of chemical species takes the form of a Markovian random walk in the *M*-dimensional space of molecular populations.
 - Exact method to solve chemical reaction systems.
 - It is always valid when the deterministic approach is valid and sometimes valid when the deterministic approach is not valid.
 - ▶ Needs to be used when small numbers of molecules.
 - Time consuming to solve larger systems.
 - ▶ There are several ways to speed up the SSA, but we discuss only the methods based on stochastic differential equations.

Stochastic modeling

- ▶ Stochastic differential equations (SDEs) characterize the time-evolution of chemical species as continuous-state stochastic process.
 - Approximate method.
 - Cannot be used when concentrations are small, good for larger concentrations when stochasticity is still important.

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• M chemical species $\rightarrow M$ differential equations.

Noise exists in all dissipative systems. Thus, variables describing the state of the system with noise are random entities. Evolution of the system is a **stochastic process**. **Intrinsic noise**

The system usually consists of many micro-particles. Macro-level variables of the system is always subject to heat fluctuations. Finite number of variables in a mathematical model and quantum nature of micro-particles are also sources of noise.

Extrinsic noise

On the other hand, the dynamical system describes a real process at some desired level. The system is usually separated from the surrounding environment. In this case, extrinsic noise influence the system (external stochastic force).

1. Stochastic differential equations

$$\dot{x}_{\xi} = f(x_{\xi}, \xi(t)) \,,$$

where $\xi(t)$ is sequence of randomly generated numbers. Thus, evolution operator becomes random in time: mapping $x_{\xi} \to x_{\xi}(t + dt)$ depends on concrete choice of $\xi(t)$ and, hence, $x_{\xi}(t)$ is a stochastic process.

The same initial conditions give different resulting trajectory $x_{\xi}(t)$. \Rightarrow one should consider *statistical ensemble* which is determined by the perturbing source $\xi_j(t)$, j = 1, 2, ..., N. For $N \to \infty$ statistical ensemble determines the stochastic process.

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2. Probability and probability density distributions One can measure realizations of a stochastic process x_1, x_2, \ldots, x_n in time moments t_1, t_2, \ldots, t_n and then take joint probability $p(x_1, t_1; x_2, t_2; \ldots; x_n, t_n)$ of their appearance. Evolution of the system is based on deterministic equations with probabilities and probability densities as variables.

$$\frac{\partial}{\partial t}p = \mathbf{L}p$$

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L is linear evolution operator. We, as most of others, will consider **L** which "does not remember previous states" (Markovian process).

Chemical Master Equation (CME)

Notation needed to formulate CME:

- ► The function \mathbf{X} : $\mathbb{R}_+ \to \mathbb{Z}^M$ describes the *M* variables (numbers of molecules of each chemical species).
- ► The system is in state X(t) = x at time t meaning that there is x numbers of molecules of each chemical species at time t.
- Reaction constants are viewed as "reaction probabilities per unit time" instead of "reaction rates":
 - c_{μ} characterizes reaction $\mathbf{R}_{\mu}, \mu \in \{1, \ldots, N\}$:
 - $c_{\mu}dt :=$ the average probability that a randomly selected combination of reaction R_{μ} reactants in V at time t will react accordingly in the infinitesimal time interval [t, t + dt).

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The value for c_{μ} can be found using molecular collision rate and Maxwell's velocity. However, the relationship between deterministic rate constant k and stochastic reaction constant c is rather simple.

Other entities needed are

 $h_{\mu}(\mathbf{x}) :=$ the number of possible reactant combinations of a reaction R_{μ} in V at time t with $\mathbf{X}(t) = \mathbf{x}$.

and

 $\boldsymbol{\nu}_{\mu}$:= the state-change vector (stoichiometric vector) defining the change in the state $\mathbf{X}(t) = \mathbf{x}$ caused by a reaction R_{μ} .

The propensity function a_{μ} is defined as

 $a_{\mu}(c_{\mu}, \mathbf{x})$ dt := the probability that a reaction R_{μ} in Vwill occur in the infinitesimal time interval [t, t + dt) given that the system is in the state $\mathbf{X}(t) = \mathbf{x}$ at time t,

meaning that

$$a_{\mu}(c_{\mu}, \mathbf{x}) := c_{\mu}h_{\mu}(\mathbf{x}).$$

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The stochastic formulation proceeds by considering the **probability function** $P(\mathbf{X}(t) = \mathbf{x} | \mathbf{X}(t_0) = \mathbf{x}_0)$ marked here briefly as $P(\mathbf{x}, t | \mathbf{x}_0, t_0)$:

 $P(\mathbf{x}, t | \mathbf{x}_0, t_0) := \text{the probability to be in the state } \mathbf{X}(t) = \mathbf{x}$ in V at time t given that the system is in the state $\mathbf{X}(t_0) = \mathbf{x}_0$ at time t_0 . (1)

In the infinitesimal time interval [t, t + dt) either zero or one reaction occurs. Thus, there exists N + 1 distinct, mutually exclusive routes (N reactions) from the state $\mathbf{X}(t) = \mathbf{x} - \nu_{\mu}$ ($\mu \in \{1, ..., N\}$) or $\mathbf{X}(t) = \mathbf{x}$ (in case of no reaction) to the state $\mathbf{X}(t + dt) = \mathbf{x}$. The probability that any of these routes takes place can be calculated by summing their distinct probabilities.

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The probability $P(\mathbf{x}, t + dt | \mathbf{x}_0, t_0)$ can be written as follows $P(\mathbf{x}, t + dt | \mathbf{x}_0, t_0) = P(\mathbf{x}, t | \mathbf{x}_0, t_0) P(\text{no reaction in } [t, t + dt))$ $+ \sum_{\mu=1}^{N} P(\mathbf{x} - \boldsymbol{\nu}_{\mu}, t | \mathbf{x}_0, t_0) P(\text{one reaction } R_{\mu} \text{ in } [t, t + dt)).$

Since in the first term no reaction is occurring in the infinitesimal time interval [t, t + dt), it means that the system has to be in state x already at time t. Thus, in the first term, the probability that the system was in the state $\mathbf{X}(t_0) = \mathbf{x}_0$ at t_0 and is in the state $\mathbf{X}(t) = \mathbf{x}$ at t is multiplied by the probability that no reaction occurs in the infinitesimal time interval [t, t + dt).

The second term is the sum of N routes where one reaction R_{μ} occurs in the infinitesimal time interval [t, t + dt). The probability that the system was in the state $\mathbf{X}(t_0) = \mathbf{x}_0$ at t_0 and is in the state $\mathbf{X}(t) = \mathbf{x} - \boldsymbol{\nu}_{\mu}$ at t is multiplied by the probability that one reaction R_{μ} (which will change state from $\mathbf{x} - \boldsymbol{\nu}_{\mu}$ to \mathbf{x}) occurs in the infinitesimal time interval [t, t + dt). It can be seen that

$$P(\text{no reaction in } [t, t + dt)) = 1 - \sum_{\mu=1}^{N} a_{\mu}(c_{\mu}, \mathbf{x}) dt$$

and

$$P(\text{one reaction } R_{\mu} \text{ in } [t, t + dt)) = a_{\mu}(c_{\mu}, \mathbf{x} - \boldsymbol{\nu}_{\mu}) dt.$$

Now we can write

$$P(\mathbf{x}, t + dt | \mathbf{x}_0, t_0) = P(\mathbf{x}, t | \mathbf{x}_0, t_0) \left(1 - \sum_{\mu=1}^{N} a_{\mu}(c_{\mu}, \mathbf{x}) dt\right)$$

+
$$\sum_{\mu=1}^{N} P(\mathbf{x} - \boldsymbol{\nu}_{\mu}, t | \mathbf{x}_{0}, t_{0}) a_{\mu}(c_{\mu}, \mathbf{x} - \boldsymbol{\nu}_{\mu}) \mathrm{d}t.$$

The Chemical Master Equation is obtained

$$\begin{aligned} \frac{\partial P(\mathbf{x},t \mid \mathbf{x}_0, t_0)}{\partial t} &\equiv \lim_{\mathrm{d}t \to 0} \frac{P(\mathbf{x},t + \mathrm{d}t \mid \mathbf{x}_0, t_0) - P(\mathbf{x},t \mid \mathbf{x}_0, t_0)}{\mathrm{d}t} \\ &= \sum_{\mu=1}^{N} \left[a_{\mu}(c_{\mu}, \mathbf{x} - \boldsymbol{\nu}_{\mu}) P(\mathbf{x} - \boldsymbol{\nu}_{\mu},t \mid \mathbf{x}_0, t_0) \right. \\ &- a_{\mu}(c_{\mu}, \mathbf{x}) P(\mathbf{x},t \mid \mathbf{x}_0, t_0) \right]. \end{aligned}$$

Chemical master equation describes the time evolution of the probability of a chemical system to occupy each one of the discrete set of states.

The chemical master equation is usually intractable, both analytically and numerically. The **Gillespie stochastic simulation algorithm** is a computer algorithm for numerical simulation of the process that chemical master equation describes.

Simple example The CME for reaction

 $\mathbf{A} \xrightarrow{c} \emptyset$

can be given with the help of (x is the number of molecules A)

$$\mathbf{x} + 1 \rightarrow \mathbf{x} \rightarrow \mathbf{x} - 1, \quad a_{\mu}(x) = cx, \quad \nu_{\mu} = -1.$$

The CME has the form

$$\frac{\partial P(\mathbf{x}, t \mid \mathbf{x}_0, t_0)}{\partial t} = \sum_{\mu=1}^{1} \left(a_{\mu}(\mathbf{x} - \nu_{\mu}) P(\mathbf{x} - \nu_{\mu}, t \mid \mathbf{x}_0, t_0) - a_{\mu}(\mathbf{x}) P(\mathbf{x}, t \mid \mathbf{x}_0, t_0) \right)$$

= $c(x+1) P(\mathbf{x}+1, t \mid \mathbf{x}_0, t_0) - cx P(\mathbf{x}, t \mid \mathbf{x}_0, t_0).$

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Linear system is a special case: Reaction A $\xrightarrow{c} \emptyset$ has the CME

$$\frac{\partial P(\mathbf{x}, t \mid \mathbf{x}_0, t_0)}{\partial t} = c(x+1)P(\mathbf{x}+1, t \mid \mathbf{x}_0, t_0) - cxP(\mathbf{x}, t \mid \mathbf{x}_0, t_0).$$

Using mathematical induction, it is possible to show that

$$P(\mathbf{x}, t \mid \mathbf{x}_0, t_0) = \frac{\mathbf{x}_0!}{\mathbf{x}!(\mathbf{x}_0 - \mathbf{x})!} e^{-c\mathbf{x}t} (1 - e^{-ct})^{\mathbf{x}_0 - \mathbf{x}}.$$

Mean is

$$E(\mathbf{X}) = \sum_{\mathbf{x}=0}^{\mathbf{x}_0} \mathbf{x} P(\mathbf{x}, t \mid \mathbf{x}_0, t_0) = \sum_{\mathbf{x}=0}^{\mathbf{x}_0} \mathbf{x} \frac{\mathbf{x}_0!}{\mathbf{x}!(\mathbf{x}_0 - \mathbf{x})!} e^{-cxt} (1 - e^{-ct})^{\mathbf{x}_0 - \mathbf{x}} =$$

$$= x_0 e^{-ct} \sum_{x=1}^{x_0} \frac{(x_0 - 1)!}{(x - 1)!(x_0 - 1 - (x - 1))!} (e^{-ct})^{x - 1} (1 - e^{-ct})^{x_0 - 1 - (x - 1)} =$$
$$= x_0 e^{-ct} \quad \text{(This is solution of the deterministic ODE)}.$$

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Gillespie stochastic simulation algorithm is a way to simulate the system at state $\mathbf{X}(t)$ to state $\mathbf{X}(t + \tau)$ in a stochastic manner by randomly selecting

- 1. what is the next reaction time moment τ and
- 2. which reaction R_{μ} that happens at the time interval $(t + \tau, t + \tau + d\tau)$.

This problem can be solved using **reaction probability density function**.

In the SSA, the probability function $P(\mathbf{x}, t | \mathbf{x}_0, t_0)$ defined in Equation 1 is not used but instead a joint probability density function $p(\tau, \mu | \mathbf{x}, t)$ of two random variables, τ and μ .

The joint probability density function is defined as

 $p(\tau, \mu \mid \mathbf{x}, t) d\tau := \text{the probability that the next reaction in } V$ will occur in the differential time interval $[t + \tau, t + \tau + d\tau) \text{ and will be a reaction } R_{\mu}$ given that the system is in the state $\mathbf{X}(t) = \mathbf{x}$ at time t, when $\tau \in [0, \infty)$ and $\mu \in \{1, \dots, N\}$

 $p(\tau, \mu | \mathbf{x}, t) d\tau$ can be defined as the probability of no reaction occurring in the time interval $[t, t + \tau)$, denoted by $P_0(\tau | \mathbf{x}, t)$, multiplied by the probability that R_{μ} will occur in the infinitesimal time interval $[t + \tau, t + \tau + d\tau)$, denoted by $a_{\mu} d\tau$:

$$p(\tau, \mu \,|\, \mathbf{x}, t) \mathrm{d}\tau = P_0(\tau \,|\, \mathbf{x}, t) a_\mu(c_\mu, \mathbf{x}) \mathrm{d}\tau.$$

Next, the formula for $P_0(\tau | \mathbf{x}, t)$ is solved. The probability that no reaction occurs in $[t, t + \tau + d\tau)$ is

$$P_0(\tau + \mathrm{d}\tau \,|\, \mathbf{x}, t) = P_0(\tau \,|\, \mathbf{x}, t) \big(1 - \sum_{\mu=1}^N a_\mu(c_\mu, \mathbf{x}) \mathrm{d}\tau \big),$$

where the first term is the probability that no reaction occurs in $[t, t + \tau)$ and the second term is the probability that no reaction occurs in $[t + \tau, t + \tau + d\tau)$. It is obtained that

$$\frac{\mathrm{d}P_0(\tau \mid \mathbf{x}, t)}{\mathrm{d}\tau} = \lim_{\mathrm{d}\tau \to 0} \frac{P_0(\tau + \mathrm{d}\tau \mid \mathbf{x}, t) - P_0(\tau \mid \mathbf{x}, t)}{\mathrm{d}\tau}$$
$$= -a_0(c_\mu, \mathbf{x})P_0(\tau \mid \mathbf{x}, t),$$

where $a_0(c_{\mu}, \mathbf{x}) = \sum_{\mu=1}^{N} a_{\mu}(c_{\mu}, \mathbf{x})$. The solution with the initial condition $P_0(\tau = 0 | \mathbf{x}, t) = 1$ is

$$P_0(\tau \mid \mathbf{x}, t) = e^{-a_0(c_\mu, \mathbf{x})\tau}.$$

$$p(\tau, \mu \mid \mathbf{x}, t) \mathrm{d}\tau = P_0(\tau \mid \mathbf{x}, t) a_\mu(c_\mu, \mathbf{x}) \mathrm{d}\tau.$$

Finally it is concluded that the joint probability function has the form

$$p(\tau, \mu \,|\, \mathbf{x}, t) = \begin{cases} a_{\mu}(c_{\mu}, \mathbf{x})e^{-a_{0}(c_{\mu}, \mathbf{x})\tau} & \text{if } \tau \in [0, \infty) \text{ and} \\ \mu \in \{1, \dots, N\}, \\ 0 & \text{otherwise,} \end{cases}$$

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where
$$a_0(c_{\mu}, \mathbf{x}) = \sum_{\mu=1}^{N} a_{\mu}(c_{\mu}, \mathbf{x}).$$

The joint probability density function can be given in form $p_{\tau,\mu}(\tau,\mu) = p_{\tau}(\tau)p_{\mu|\tau}(\mu|\tau)$, where $p_{\tau}(\tau)d\tau$ is the probability that the next reaction will occur in $[t + \tau, t + \tau + d\tau)$ regardless of which reaction it might be and $p_{\mu|\tau}(\mu|\tau)$ is the probability that the next reaction will be R_{μ} given that it occurs at time $t + \tau$:

$$p_{\tau}(\tau) = \begin{cases} \sum_{\mu=1}^{N} p_{\tau,\mu}(\tau,\mu) & \text{if } \tau \in [0,\infty), \\ 0 & \text{otherwise}, \end{cases}$$
$$= \begin{cases} \sum_{\mu=1}^{N} a_{\mu}e^{-a_{0}\tau} & \text{if } \tau \in [0,\infty), \\ 0 & \text{otherwise}, \end{cases}$$
$$= \begin{cases} a_{0}e^{-a_{0}\tau} & \text{if } \tau \in [0,\infty), \\ 0 & \text{otherwise}, \end{cases}$$

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and

$$p_{\mu|\tau}(\mu|\tau) = \begin{cases} \frac{p_{\tau,\mu}(\tau,\mu)}{N} & \text{if } \mu \in \{1,\dots,N\}, \\ \sum_{\mu'=1}^{N} p_{\tau,\mu}(\tau,\mu') & \\ 0 & \text{otherwise}, \end{cases}$$
$$= \begin{cases} \frac{a_{\mu}e^{-a_{0}\tau}}{N} & \text{if } \mu \in \{1,\dots,N\}, \\ \sum_{\mu'=1}^{N} a_{\mu'}e^{-a_{0}\tau} & \\ 0 & \text{otherwise}, \end{cases}$$
$$= \begin{cases} \frac{a_{\mu}}{a_{0}} & \text{if } \mu \in \{1,\dots,N\}, \\ 0 & \text{otherwise}. \end{cases}$$
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Each probability density function depends only on one of the two parameters, $p_{\mu \mid \tau}(\mu \mid \tau) = p_{\mu \mid \tau}(\mu)$.

There are several ways to implement the exact SSA. In **the direct method**, with two random numbers r_1 and r_2 uniformly distributed on the interval [0, 1], the time interval $[t, t + \tau)$ is determined according to Equation 2 and the reaction R_{μ} is determined according to Equation 3. The probability distribution function F_{τ} is

$$F_{\tau}(\tau \mid \mathbf{x}, t) = \int_{-\infty}^{\tau} p_{\tau}(\tau' \mid \mathbf{x}, t) \mathrm{d}\tau' = \int_{0}^{\tau} p_{\tau}(\tau' \mid \mathbf{x}, t) \mathrm{d}\tau'$$
$$= \int_{0}^{\tau} a_{0} e^{-a_{0}\tau'} \mathrm{d}\tau' = 1 - e^{-a_{0}(c_{\mu}, \mathbf{x})\tau}.$$

Because $F_{\tau}(\tau) \in [0, 1]$, it is possible to mark $r_1 = F_{\tau}(\tau) = 1 - e^{-a_0\tau}$. By replacing the random number $1 - r_1$ by the statistically equivalent random number r_1 , $r_1 = e^{-a_0\tau}$ is obtained. Now $\ln(r_1) = -a_0\tau$, $\tau = -\ln(r_1)/a_0$, and finally

$$\tau = \frac{1}{a_0(c_\mu, \mathbf{x})} \ln\left(\frac{1}{r_1}\right).$$

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Using Equation 3, the probability distribution function $F_{\mu|\tau}$ is

$$\begin{aligned} F_{\mu|\tau}(\mu \,|\, \mathbf{x}, t) &= \sum_{\mu'=-\infty}^{\mu} p_{\mu|\tau}(\mu' \,|\, \mathbf{x}, t) = \sum_{\mu'=1}^{\mu} p_{\mu|\tau}(\mu' \,|\, \mathbf{x}, t) \\ &= \frac{1}{a_0(c_\mu, \mathbf{x})} \sum_{\mu'=1}^{\mu} a_{\mu'}(c_\mu, \mathbf{x}). \end{aligned}$$

Taking for μ the value which satisfies $F_{\mu|\tau}(\mu-1) < r_2 \leq F_{\mu|\tau}(\mu),$

$$\sum_{\mu'=1}^{\mu-1} p_{\mu \mid \tau}(\mu' \mid \mathbf{x}, t) < r_2 \le \sum_{\mu'=1}^{\mu} p_{\mu \mid \tau}(\mu' \mid \mathbf{x}, t)$$

is obtained, and

$$\sum_{\mu'=1}^{\mu-1} a_{\mu'}(c_{\mu}, \mathbf{x}) < r_2 a_0(c_{\mu}, \mathbf{x}) \le \sum_{\mu'=1}^{\mu} a_{\mu'}(c_{\mu}, \mathbf{x}).$$

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Gillespie Algorithm (direct method)

- 1. Set t = 0. Specify initial values for $\mathbf{X} = [X_1, ..., X_M]$ and values for c_{μ} and stoichiometric vectors $\boldsymbol{\nu}_{\mu}, \mu = 1, ..., N$.
- 2. Calculate a_{μ} , $\mu = 1, ..., N$, and $a_0 = \sum_{\mu=1}^{N} a_{\mu}$.
- 3. Generate random pair (τ, μ) according to $p(\tau, \mu | \mathbf{x}, t)$: Generate two random numbers r_1 and r_2 uniformly distributed on the interval [0, 1]. Take $\tau = \frac{1}{a_0} \ln \frac{1}{r_1}$. Take μ so that $\sum_{\mu'=1}^{\mu-1} a_{\mu'} < r_2 a_0 \leq \sum_{\mu'=1}^{\mu} a_{\mu'}$.

4. Update of the system by

$$\mathbf{X}(t+\tau) = \mathbf{X}(t) + \boldsymbol{\nu}_{\mu}.$$
 (4)

5. Go to step 2 or end the simulation.

D. T. Gillespie, Journal of Computational Physics, vol. 22, no. 4, pp. 403-434, 1976. By carrying out the above procedure one obtains one possible realization of the stochastic process.

In order to get statistically complete picture of the time-evolution of the system, one must carry out several independent simulations with the same initial conditions and calculate **sample mean** and **sample standard deviation**.



Figure: Left: one realization. Right: sample mean and standard deviation of 1000 realizations (T. Manninen et al., *Computational Biology and Chemistry*, vol. 30, pp. 280–291, 2006.

Difference between ODE and SSA model construction:

- ▶ ODE: concentrations [X] in M = mol/l, $[v_{\mu}] = M/s$
- ► SSA: [X] in numbers, $[a_{\mu}] = [c_{\mu}] = 1/s$
- ► $X = N_A V[X]$, where N_A is the Avogadro's constant and V is volume.

- $\blacktriangleright \emptyset \xrightarrow{k_{\mu}} S:$
 - Reaction rate: $v_{\mu} = k_{\mu}, [k_{\mu}] = M/s$
 - Propensity: $h_{\mu} = 1, a_{\mu} = c_{\mu}, c_{\mu} = N_A V k_{\mu}$

$$S_1 \xrightarrow{k_{\mu}} S_2:$$

$$v_{\mu} = k_{\mu}[X_1], [k_{\mu}] = 1/s$$

$$h_{\mu} = X_1, a_{\mu} = c_{\mu}X_1, c_{\mu} = k_{\mu}$$

$$\begin{array}{l} \bullet \ \ {\rm S}_1 + {\rm S}_2 \xrightarrow{k_{\mu}} {\rm S}_3: \\ \bullet \ \ v_{\mu} = k_{\mu}[X_1][X_2], \, [k_{\mu}] = 1/(Ms) \\ \bullet \ \ h_{\mu} = X_1 X_2, \, a_{\mu} = c_{\mu} X_1 X_2, \, c_{\mu} = k_{\mu}/(N_A V) \\ \bullet \ \ 2{\rm S}_1 \xrightarrow{k_{\mu}} {\rm S}_2: \\ \bullet \ \ v_{\mu} = k_{\mu}[X_1]^2, \, d[X_1]/dt = -2k_{\mu}[X_1]^2, \, [k_{\mu}] = 1/(Ms) \\ \bullet \ \ h_{\mu} = X_1(X_1 - 1)/2, \, a_{\mu} = c_{\mu} X_1(X_1 - 1)/2, \, c_{\mu} = 2k_{\mu}/(N_A V) \end{array}$$



Figure: Five realizations of stochastic linear birth-death process together with the deterministic solution for two different (λ, μ) combinations, i.e., left: $\lambda = 3$, $\mu = 4$ and right: $\lambda = 7$, $\mu = 8$, each $\lambda - \mu = -1$ and $x_0 = 50$.

Stochastic Differential Equation (SDE) Models

If during any time interval $[t, t + \tau)$ all of the reactions can occur often, but none of the propensity functions a_{μ} changes significantly, then the discrete-state Markov process can be approximated by a continuous-state Markov process described by **the chemical Langevin equation (CLE)**. The number of times a reaction can happen can be defined as

 $K_{\mu}(c_{\mu}, \mathbf{x}, \tau) :=$ the number of times a reaction R_{μ} occurs in the time interval $[t, t + \tau]$ given that the system is in the state $\mathbf{X}(t) = \mathbf{x}$ at time t.

The update of the system in Equation 4 then becomes

$$\mathbf{X}(t+\tau) = \mathbf{X}(t) + \sum_{\mu=1}^{N} K_{\mu}(c_{\mu}, \mathbf{x}, \tau) \boldsymbol{\nu}_{\mu}.$$

 $K_{\mu}(c_{\mu}, \mathbf{x}, \tau)$ is of course a *random variable*. To compute it for arbitrary $\tau > 0$ would be quite as difficult as solving the master equation. But we can obtain excellent *approximation* to $K_{\mu}(c_{\mu}, \mathbf{x}, \tau)$ rather easily if we impose the following conditions:

1) Require τ to be *small* enough that the change in the state during $[t, t + \tau]$ will be so slight that none of the propensity functions changes its value "appreciably", i.e.

$$a_{\mu}(\mathbf{x}(t')) \cong a_{\mu}(\mathbf{x}(t)), \quad \forall t' \in [t, t+\tau], \quad \forall \mu \in [1, N]$$

<u>Practically</u>: all reactant molecule populations are sufficiently large compared to 1.

So we can rewrite the "update" of the system:

$$\mathbf{X}(t+\tau) = \mathbf{X}(t) + \sum_{\mu=1}^{N} \boldsymbol{\nu}_{\mu} \mathcal{P}_{\mu}(a_{\mu}(c_{\mu}, \mathbf{x}), \tau),$$

where $\mathcal{P}_{\mu}(a_{\mu}(c_{\mu}, \mathbf{x}), \tau)$ is Poisson random variable.

2) Require τ to be *large* enough that the expected number of occurrences of each reaction channel R_{μ} in $[t, t + \tau]$ be much larger than 1, i.e.

$$\langle \mathcal{P}_{\mu}(a_{\mu}(c_{\mu}, \mathbf{x}), \tau) \rangle = a_{\mu}(c_{\mu}, \mathbf{x}) \times \tau \gg 1, \quad \forall \mu \in [1, N].$$

Obviously, this condition runs counter to condition 1. <u>Practically</u>: $a_{\mu}(c_{\mu}, \mathbf{x})$ is proportional to $h_{\mu}(\mathbf{x})$ and thus to one or more components of \mathbf{x} , thus, sufficiently large molecular populations can make the condition 2 to hold even when τ is small.

This condition allows us to *approximate* each Poisson random variable $\mathcal{P}_{\mu}(a_{\mu}(c_{\mu}, \mathbf{x}), \tau)$ by a *normal* random variable with the same mean and variance.

So the update of the system:

$$\mathbf{X}(t+\tau) = \mathbf{X}(t) + \sum_{\mu=1}^{N} \boldsymbol{\nu}_{\mu} \mathcal{N}_{\mu}(a_{\mu}(c_{\mu}, \mathbf{x})\tau, a_{\mu}(c_{\mu}, \mathbf{x})\tau)$$

where $\mathcal{N}(m, \sigma^2)$ denotes the normal random variable with mean m and variance σ^2 .

Further modifying the update (using the linear combination theorem for normal random variables: $\mathcal{N}(n, \sigma^2) = m + \sigma \mathcal{N}(0, 1)$):

$$\mathbf{X}(t+\tau) = \mathbf{X}(t) + \sum_{\mu=1}^{N} \boldsymbol{\nu}_{\mu} \mathcal{N}_{\mu} \left(a_{\mu}(c_{\mu}, \mathbf{x}) \tau, a_{\mu}(c_{\mu}, \mathbf{x}) \tau \right) =$$

$$= \mathbf{X}(t) + \sum_{\mu=1}^{N} \boldsymbol{\nu}_{\mu} a_{\mu} (c_{\mu}, \mathbf{X}(t)) \tau + \sum_{\mu=1}^{N} \boldsymbol{\nu}_{\mu} \sqrt{a_{\mu} (c_{\mu}, \mathbf{X}(t)) \tau} \mathcal{N}_{\mu}(0, 1) =$$

$$= \mathbf{X}(t) + \sum_{\mu=1}^{N} \boldsymbol{\nu}_{\mu} a_{\mu} (c_{\mu}, \mathbf{X}(t)) \tau + \sum_{\mu=1}^{N} \boldsymbol{\nu}_{\mu} \sqrt{a_{\mu} (c_{\mu}, \mathbf{X}(t))} \mathcal{N}_{\mu}(0, \tau).$$

Some implications

- Condition 1 requires that any of the propensity functions does not change appreciably. Thus, all reactions occurring in $[t, t + \tau]$ will be essentially *independent* of each other. Hence, we can approximate each $K_{\mu}(c_{\mu}, \mathbf{x}, \tau)$ with *statistically independent* Poisson random variable.
- Notice that in replacing the *integer Poisson* random variables by the *real normal* random variables (by condition 2), we in effect convert X_j from discretely changing integer variables to continuously changing real variables.
- Notice that the normal random variables \mathcal{N}_{μ} will be *statistically independent* as a consequence of statistical independence of the Poisson's \mathcal{P}_{μ} . That is why one can use Brownian motion as an approximation to \mathcal{N}_{μ} .

The chemical Langevin equation

$$d\mathbf{X}(t) = \sum_{\mu=1}^{N} \boldsymbol{\nu}_{\mu} a_{\mu} (c_{\mu}, \mathbf{X}(t)) dt + \sum_{\mu=1}^{N} \boldsymbol{\nu}_{\mu} \sqrt{a_{\mu} (c_{\mu}, \mathbf{X}(t))} d\mathbf{W}_{\mu}(t),$$

where $d\mathbf{W}(\tau) \sim \mathcal{N}(0,\tau) \equiv \sqrt{\tau} \mathcal{N}(0,1)$ is the Brownian motion.

W(0) = 0, the increment $W(t) - W(s) \sim \mathcal{N}(0, t-s)$ for all $0 \le s < t \le T$, and for all $0 \le s < t < u < v \le T$, the increments W(t) - W(s) and W(v) - W(u) are independent.

D. T. Gillespie, J. Chem. Phys., vol. 113, no. 1, pp. 297–306, 2000.

General Stochastic differential equation model

$$dx(t) = f(x(t))dt + g(x(t))dW(t)$$

can be simulated using, for example, the Euler-Maruyama \mathbf{method}

$$x(t + \Delta t) = x(t) + f(x(t))\Delta t + g(x(t))\sqrt{\Delta t}\mathcal{N}(0, 1)$$

where Δt is a small numerical integration (simulation) time step.

Higher order Milstein method can also be applied:

$$x(t + \Delta t) = x(t) + f(x(t))\Delta t + g(x(t))\sqrt{\Delta t}\mathcal{N}(0, 1) + \frac{1}{2}g(x(t))g'(x(t))\left(\mathcal{N}^{2}(0, 1) - 1\right)\Delta t.$$

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- Mean field approximation (ODE approach) does not work for small number of molecules.
- ► All molecular systems get affected by the thermal fluctuations (intrinsic noise).
- ▶ There are two fundamental approaches to stochastic systems: Chemical Master Equation (CME) and stochastic differential equations.
- CME is usually intractable, because each state of the system needs a separate ODE.
- ▶ Gillespie stochastic simulation algorithm (SSA) numerically simulates the Markov process that the CME describes analytically.